

Topic: An aeroacoustic investigation of turbulent interference of a propeller on a UAM vehicle

Presenter: Ahmed Khan



Overview

Background

Test overview and methodology

Results and discussion

Conclusions

Future work



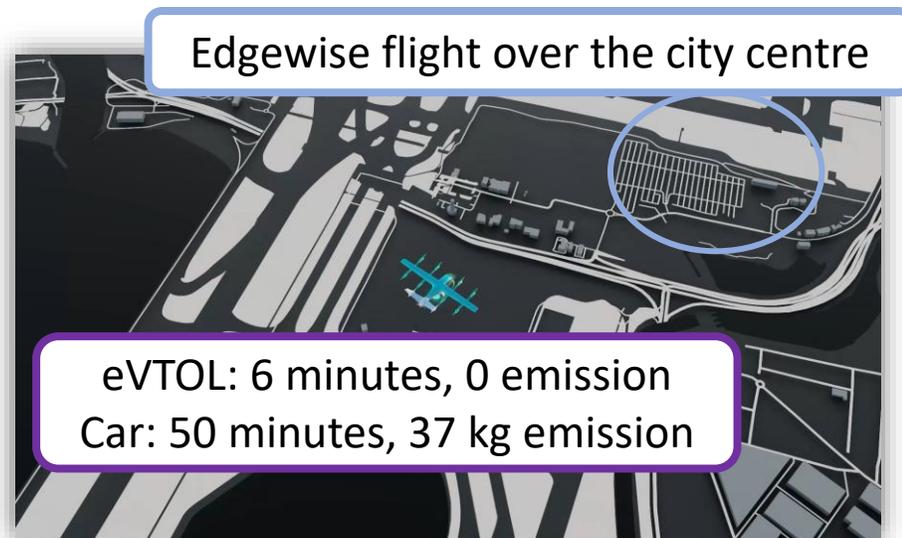
Background – UAM vehicles

Urban air mobility (UAM)

- **Green aviation** contributes to carbon neutrality and promotes technological advance
- The UAM market is estimated to be worth **\$28 Billion by 2032** ^[1]
- Electric vertical take-off and landing (**eVTOL**) provides flexibility in urban area



Vertical Aerospace VX4



Aeroacoustic challenges of UAM vehicles

- Critical barrier to **community acceptance** ^[2]
- Complex flow field makes **cost-effective prediction** difficult
- Limited experimental data to **validate** low-order models
- Limited studies carried out on turbulence interaction

[1] F. Research, Global urban air mobility market worth \$28.5 billion by 2032 (Nov 2024).

[2] D.P. Thipphavong et al., Urban Air Mobility Airspace Integration Concepts and Considerations, AIAA 2018-3676

Overview

Background of tandem-rotor noise

Test overview and methodology

Results and discussion

Conclusions

Future work



Research objective

Experimental study of **turbulence interactions** in edgewise conditions

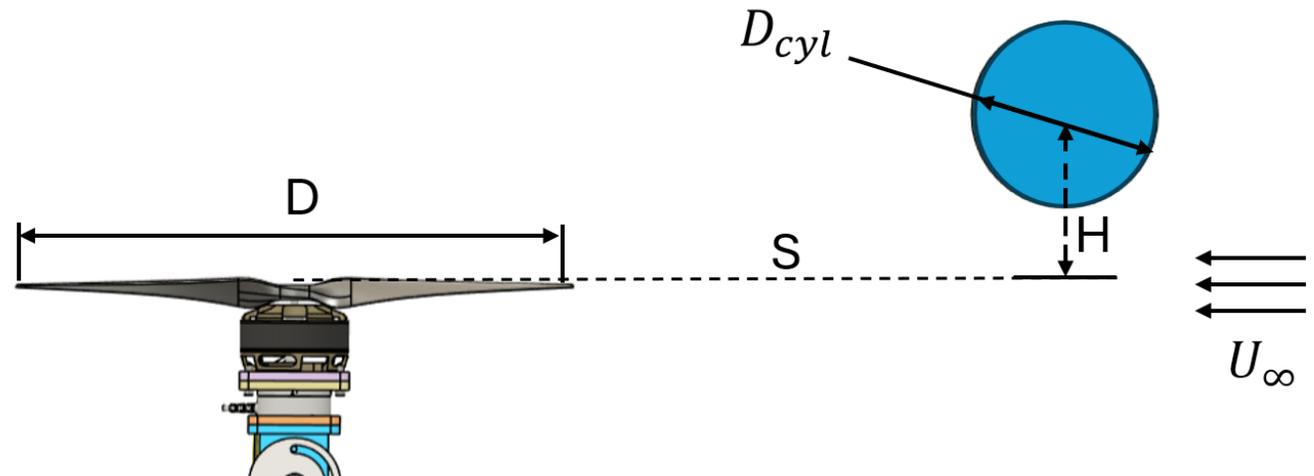
- *Aeroacoustic signatures from far-field microphones*
- *Nearfield flow measurement using phase-locked PIV*

- *Gain a better understand **Haystacking** effects*



Methodology – Test Configuration

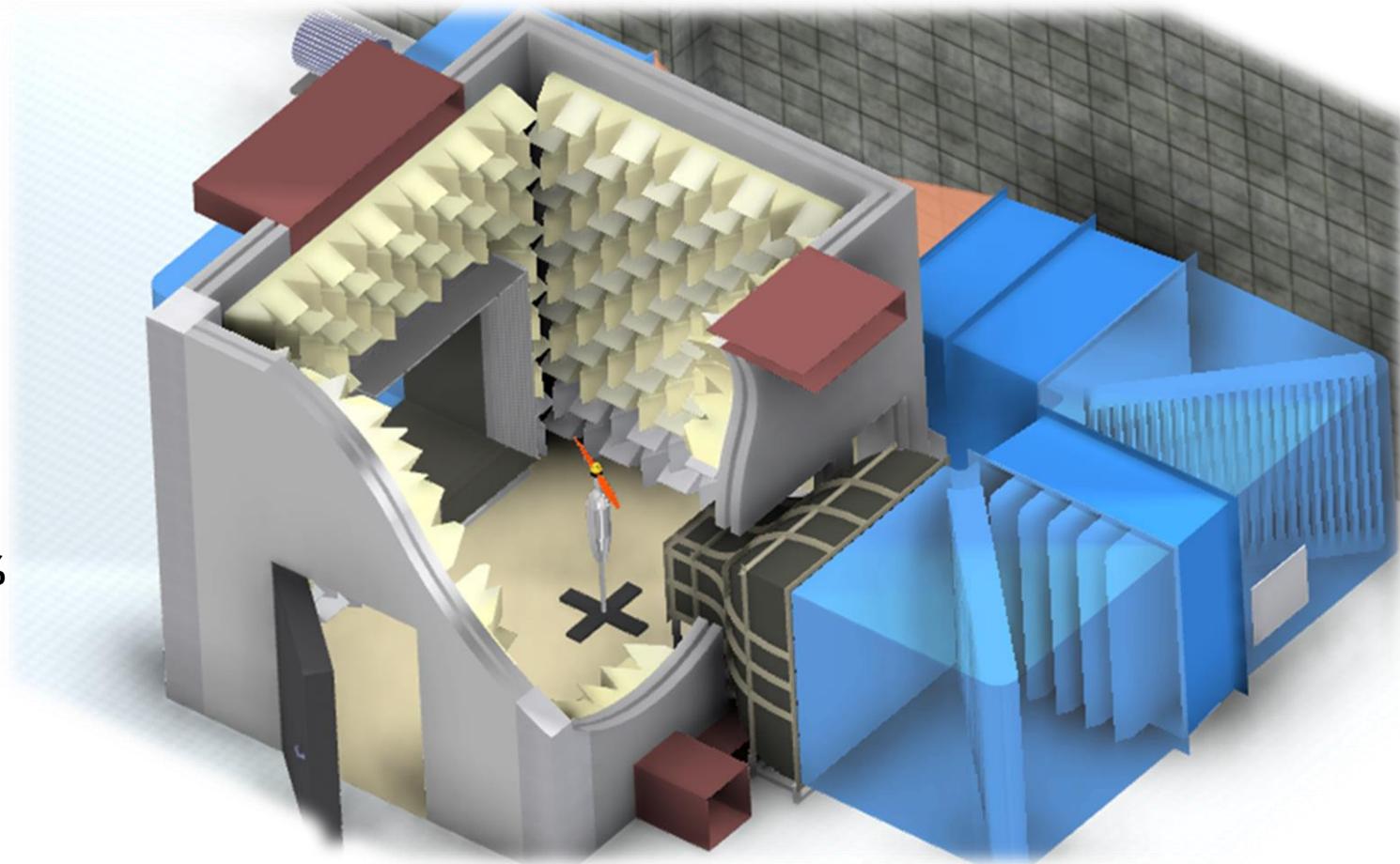
- **Free stream velocity:**
 - $U_{\infty} = 20 \text{ ms}^{-1}$
- **Propeller:**
 - $D = 302 \text{ mm}$ (12")
- **Cylinder:**
 - $H = 0, \pm 0.25D$
 - $S = 5D$
 - $D_{cyl} = 101.6 \text{ mm}$
 - $Freq_{cyl} = 40 \text{ Hz}$



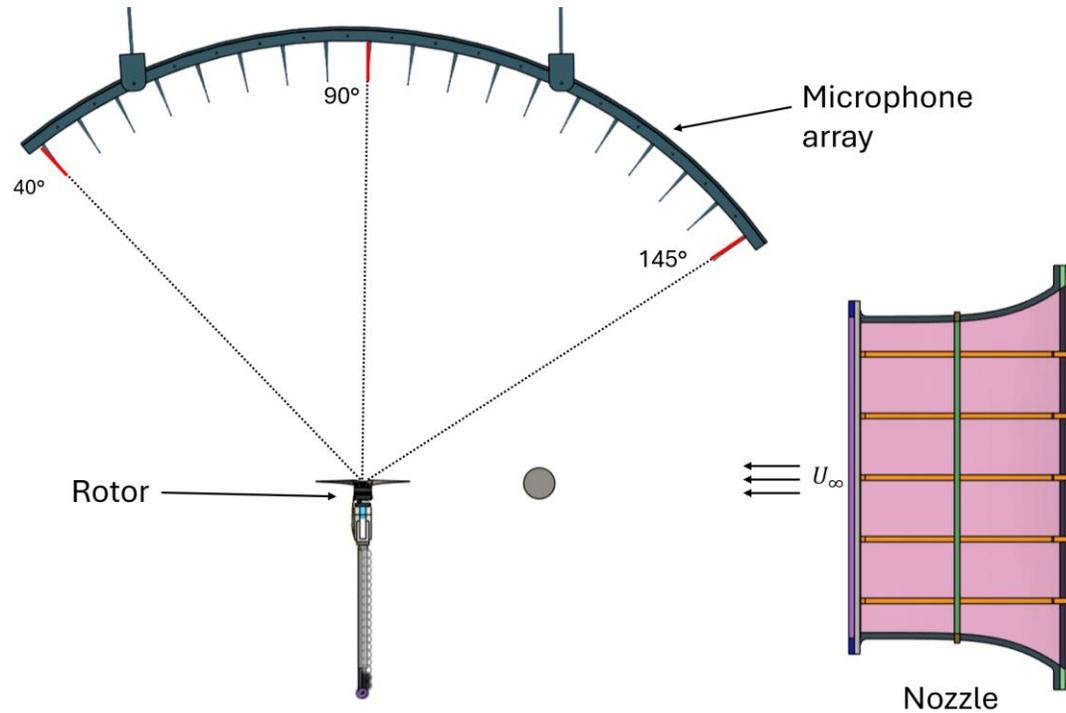
Methodology – Acoustic Test Facility

Pressure-Neutral Acoustic Wind Tunnel

- Open section, close-loop wind tunnel
- **1 m (W) x 0.7 m (H) Nozzle**
- U_{∞} range of **5 m/s to 35 m/s**
- Turbulence intensity limited to approx. **0.2%**
- **Acoustically treated** section walls



Methodology – Acoustic Instrumentation



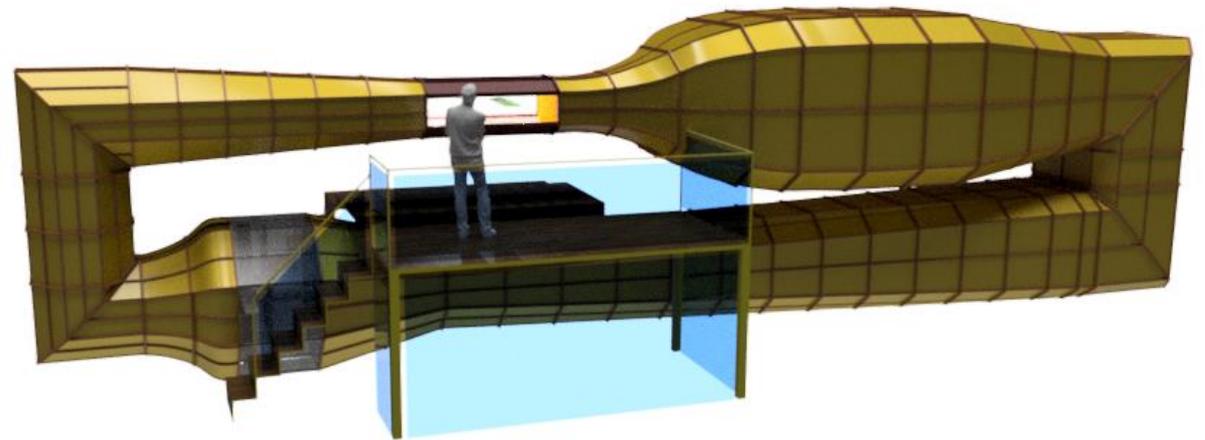
Top Array

- Coplanar with rotor
- 22 GRAS 40PL-10 microphones
- Observer range: $\theta = 40^\circ$ to 145°

Methodology – PIV Test Facility

Low Turbulence Wind Tunnel

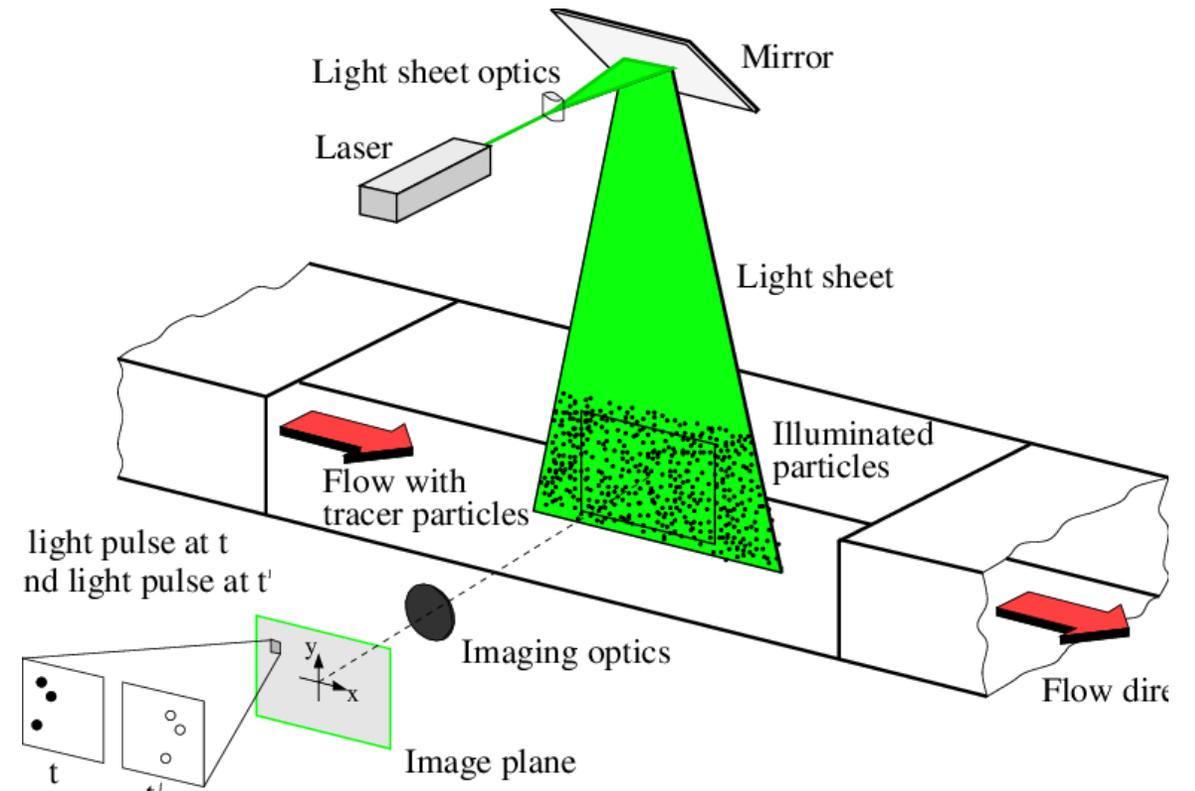
- Closed section, close-loop wind tunnel
- Octagonal shape with a **0.8 m x 0.6 m** Working section
- U_{∞} range up to **100 m/s**
- Turbulence intensity limited to approx. **0.05%**
- Fitted with a **LaVision tomographic PIV system**



Methodology – PIV Test Facilities

Particle Image Velocimetry (PIV) Explained:

- Flow field is seeded with tracer particles
- The imaging plane is illuminated using a high-power laser
- Cameras capture 2 frames of the imaging field in rapid succession
- Velocity field is resolved by calculating the displacement of tracer particles between the 2 frames

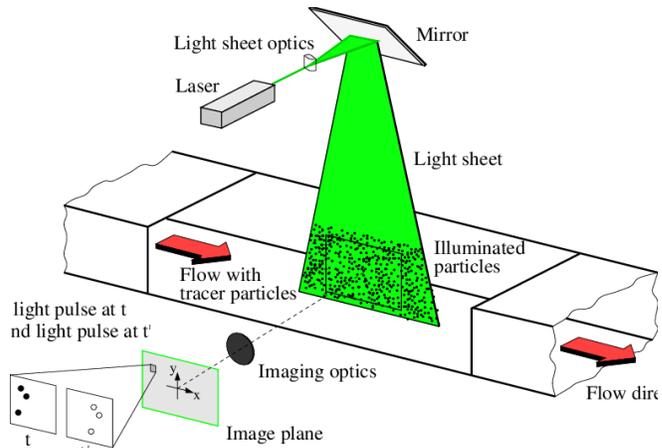


[3] - J. Kompenhans (2002). Application of Particle Image Velocimetry for the Investigation of High Speed Flow Fields.

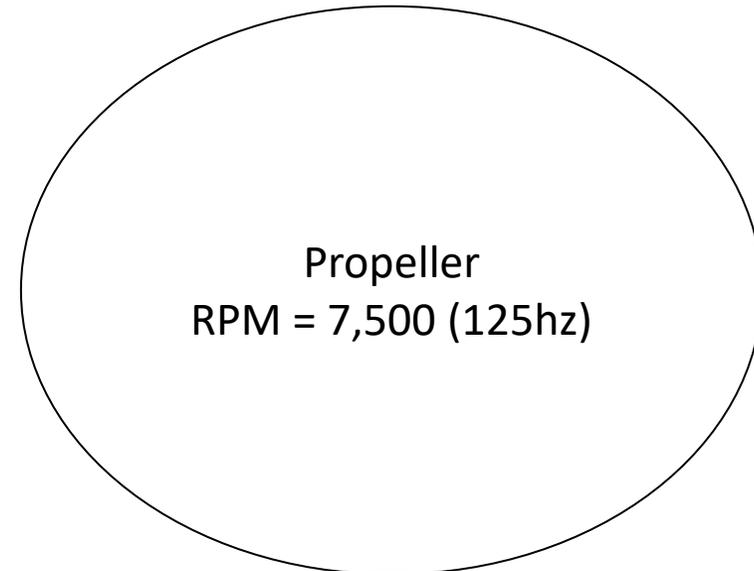
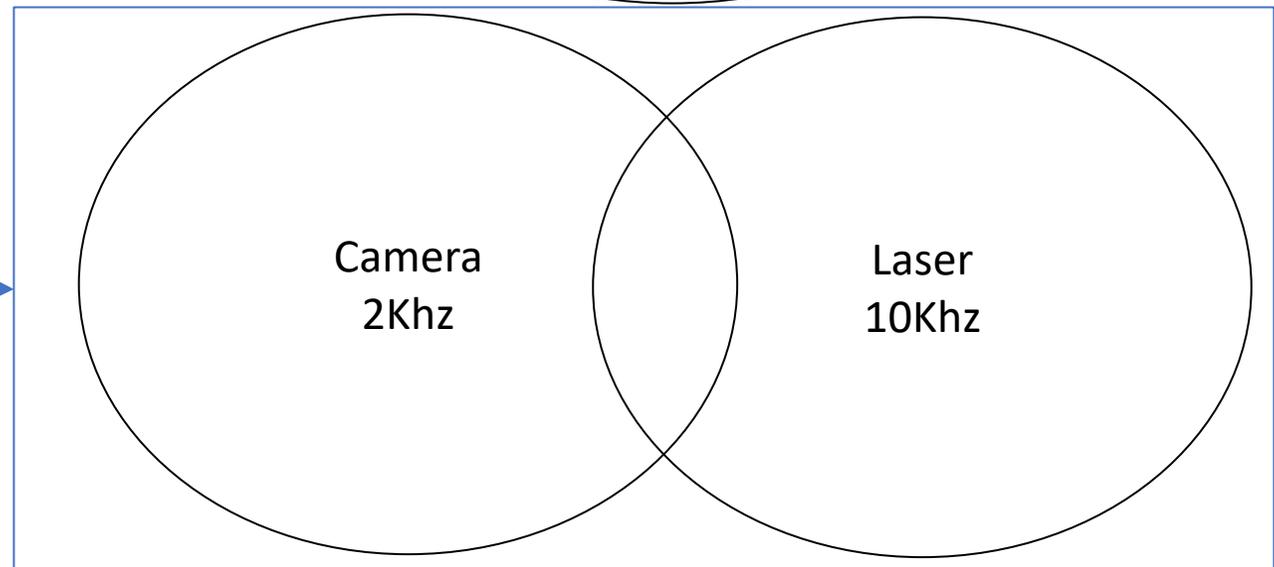
Methodology – PIV Phase locking

What is Phase locking:

- The process of synchronizing the PIV data acquisition process with the blade azimuth position.
- In this case, the data acquisition process was triggered with an external signal generator



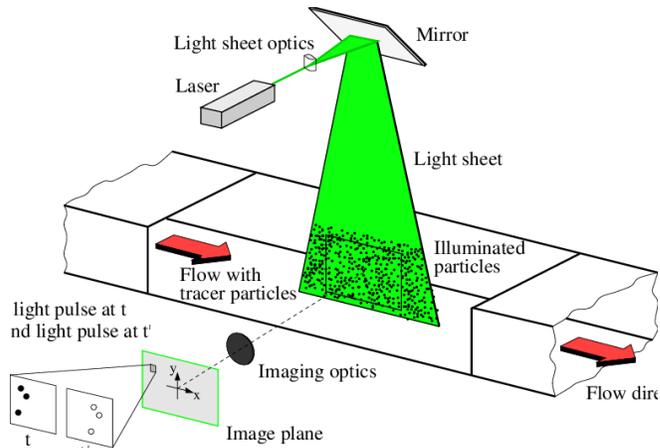
In Phase



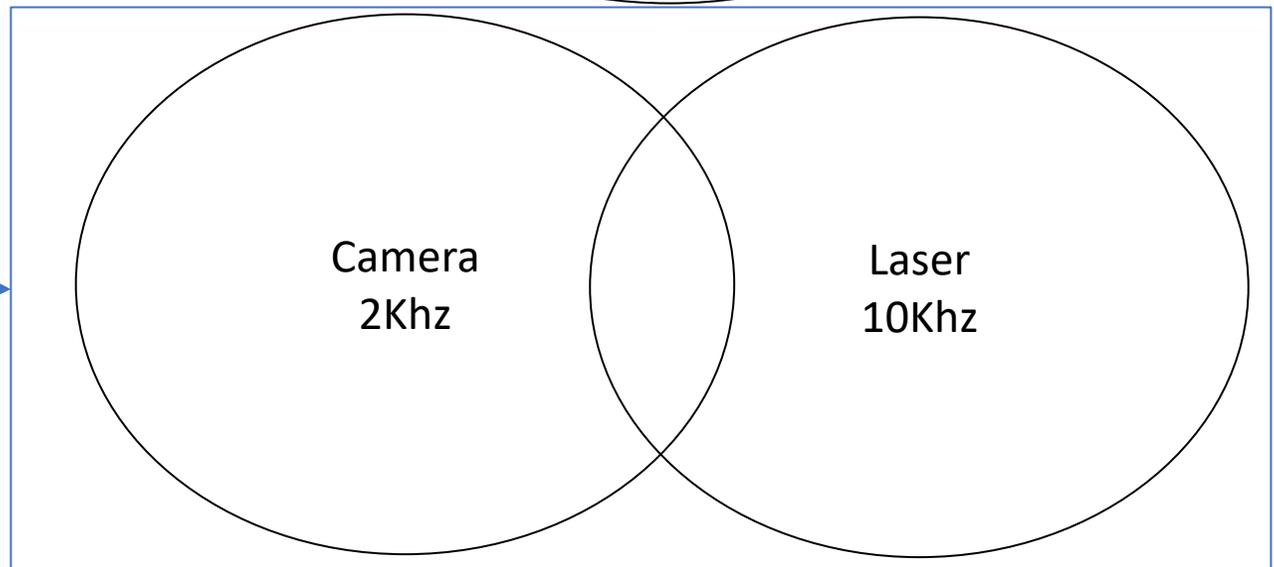
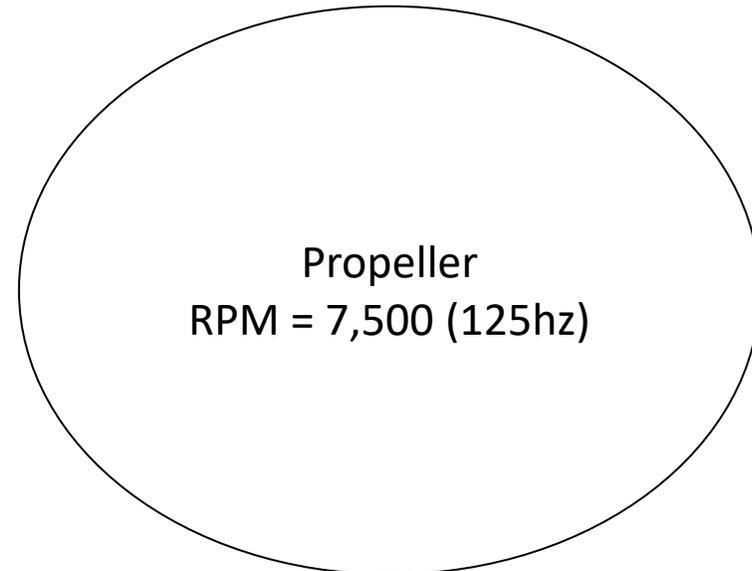
Methodology – PIV Phase locking

What is Phase locking:

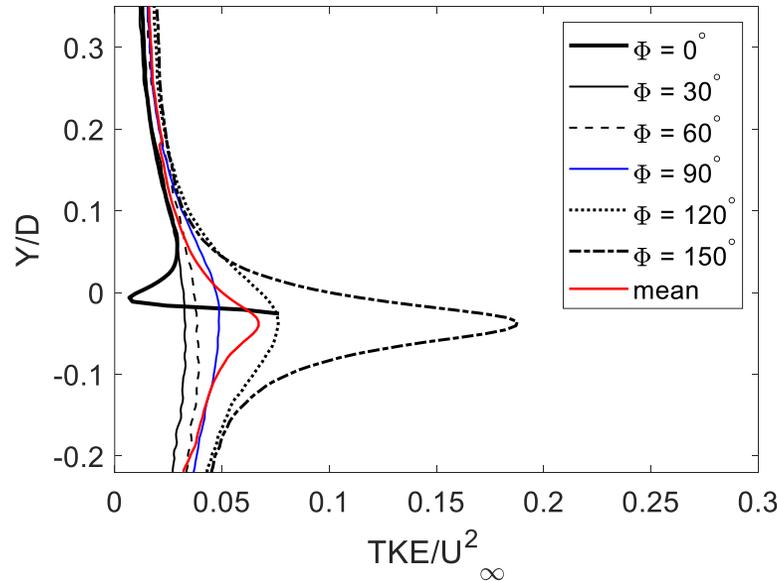
- The process of synchronizing the PIV data acquisition process with the blade azimuth position.
- In this case, the data acquisition process was triggered with an external signal generator



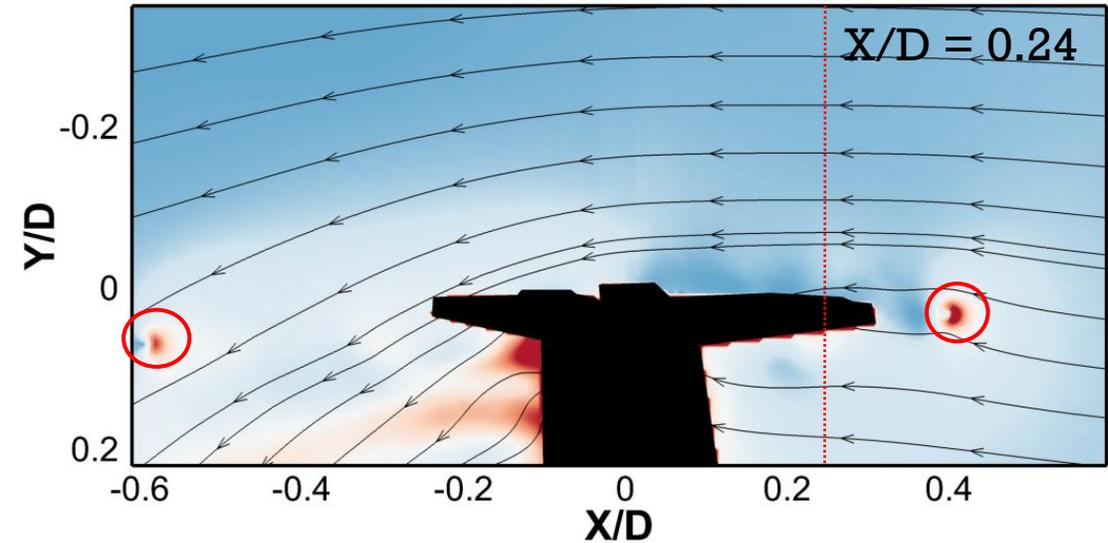
In Phase



Methodology – PIV Phase Locking



**Turbulence Intensity (Ti)
slice at Y/D = 0.24**



**Turbulence Intensity (Ti) plot of the
baseline case with velocity
streamlines ($\phi = 120^\circ$)**

Why use phase locking?

- Results in a “frozen” flow field picture
- Phase-locked measurements enable the flow evolution to be observed.

Overview

Background of tandem-rotor noise

Test overview and methodology

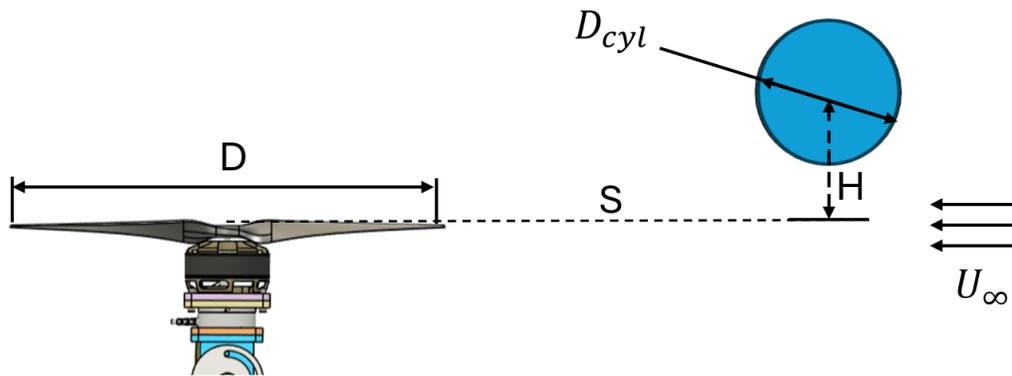
Results and discussion

Conclusions

Future work



Results and Discussion



Test case:

- 7500 RPM: High Thrust condition – Edgewise flight
- 20 m/s inflow
- $\mu = 0.167$
- $S = 5D$

Presented results:

Directivity

- Overall sound pressure level (OASPL)

Noise spectra

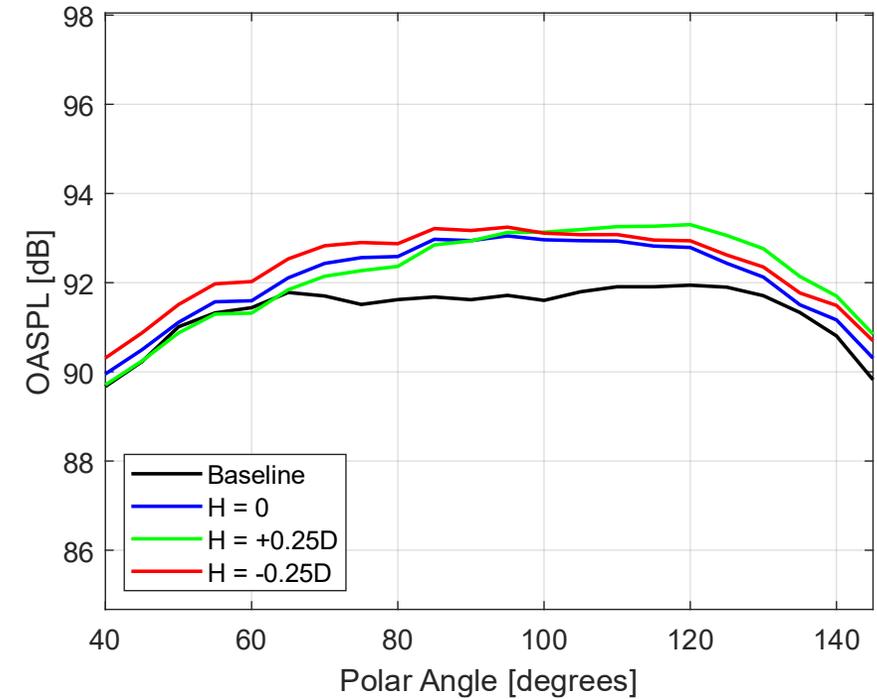
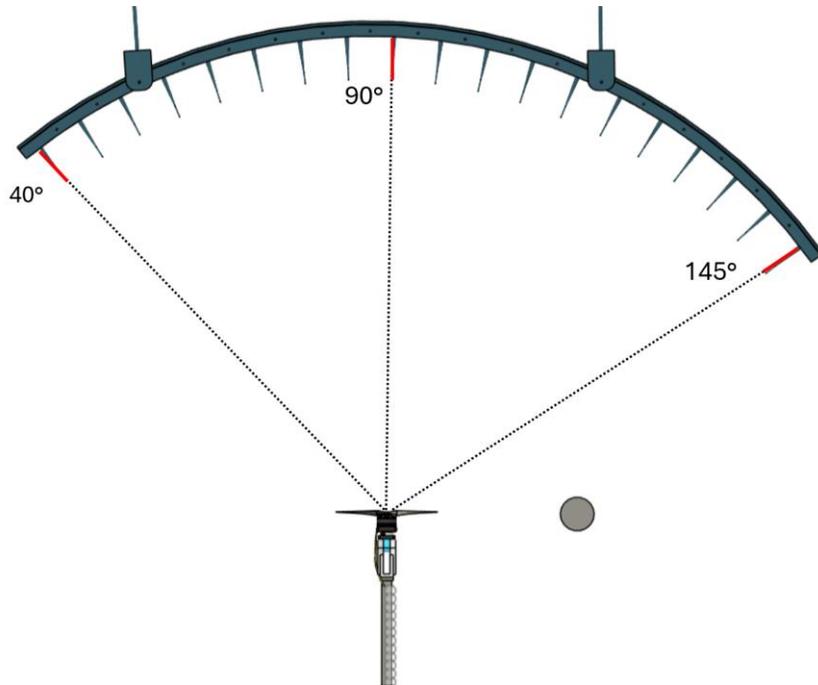
- Sound pressure levels (SPL) at 3 different cylinder heights

PIV Profiles

- Velocity profiles for $H = 0$

Results and Discussion – Far-field Noise Directivity

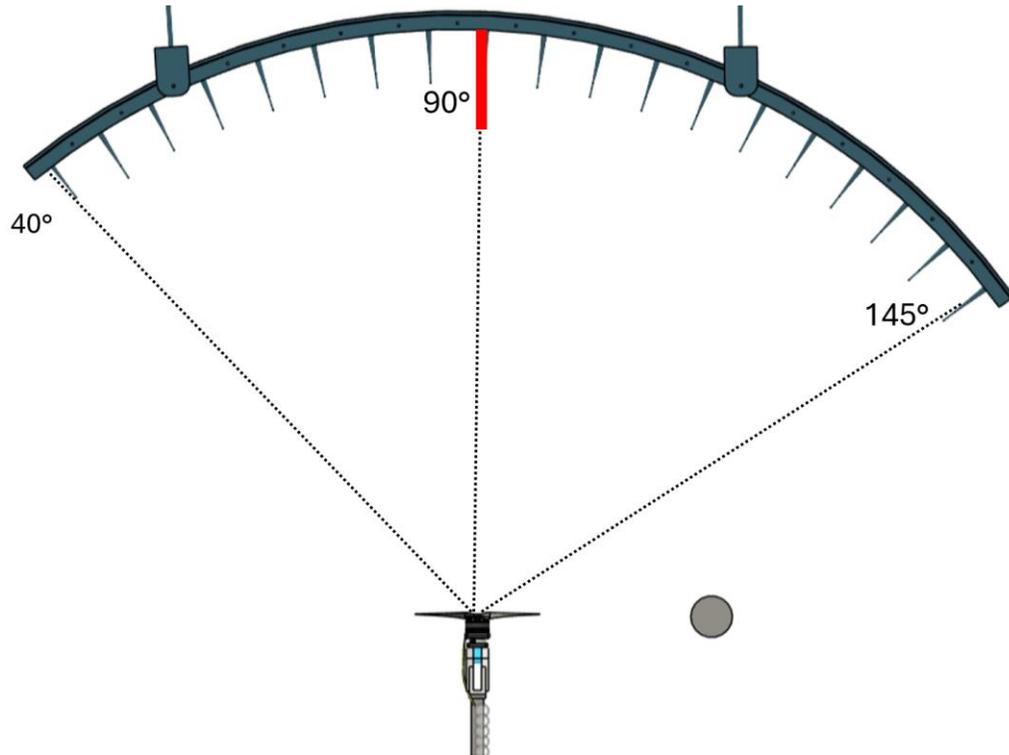
7500 RPM and 20 m/s inflow ($\mu = 0.167$)



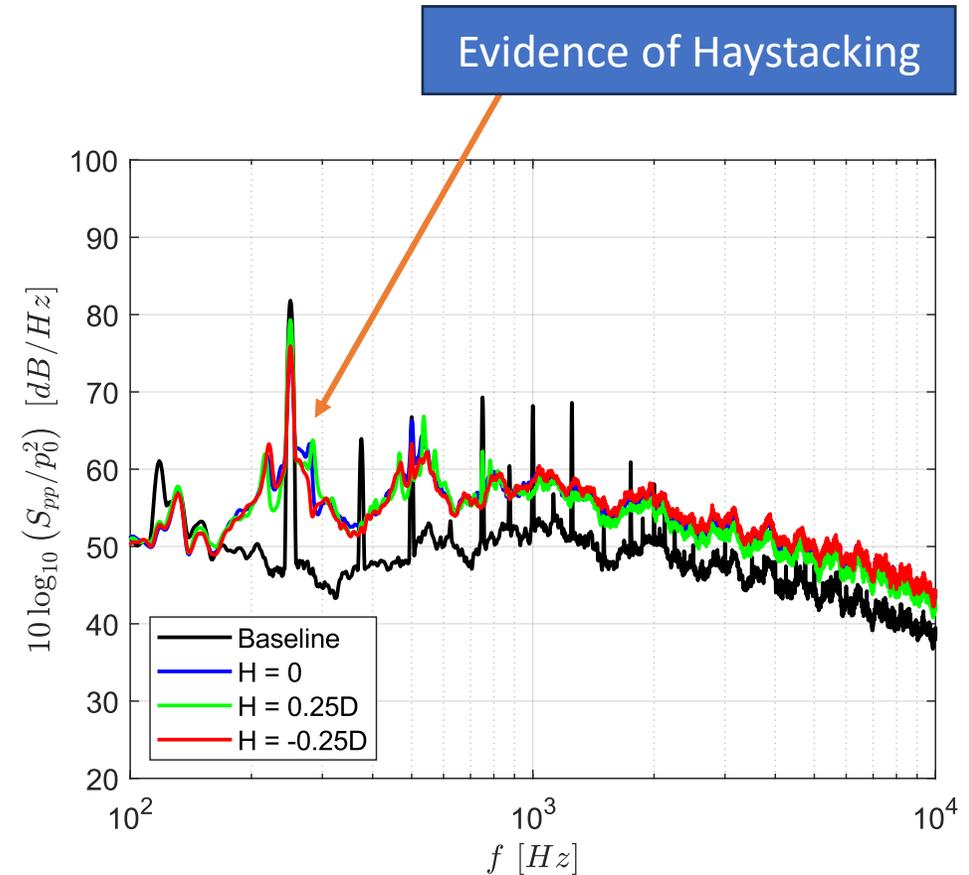
- Overall OASPL increase with all 3 cases
- H = 0 and H = -0.25D have similar sensitivities due to interactions with the motor body

Results and Discussion – Far-field Noise Spectra

7500 RPM and 20 m/s inflow ($\mu = 0.167$)



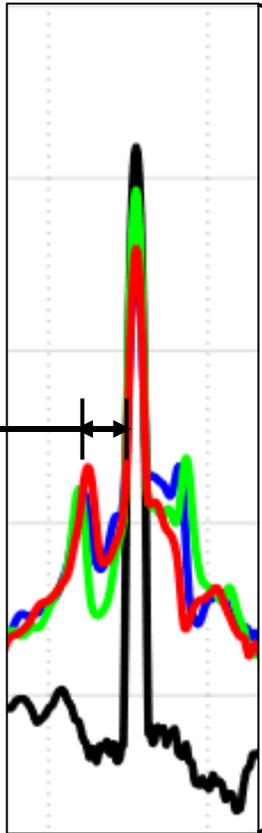
- Overall SPL increase in all 3 cases
- Haystacking observed in the BPF



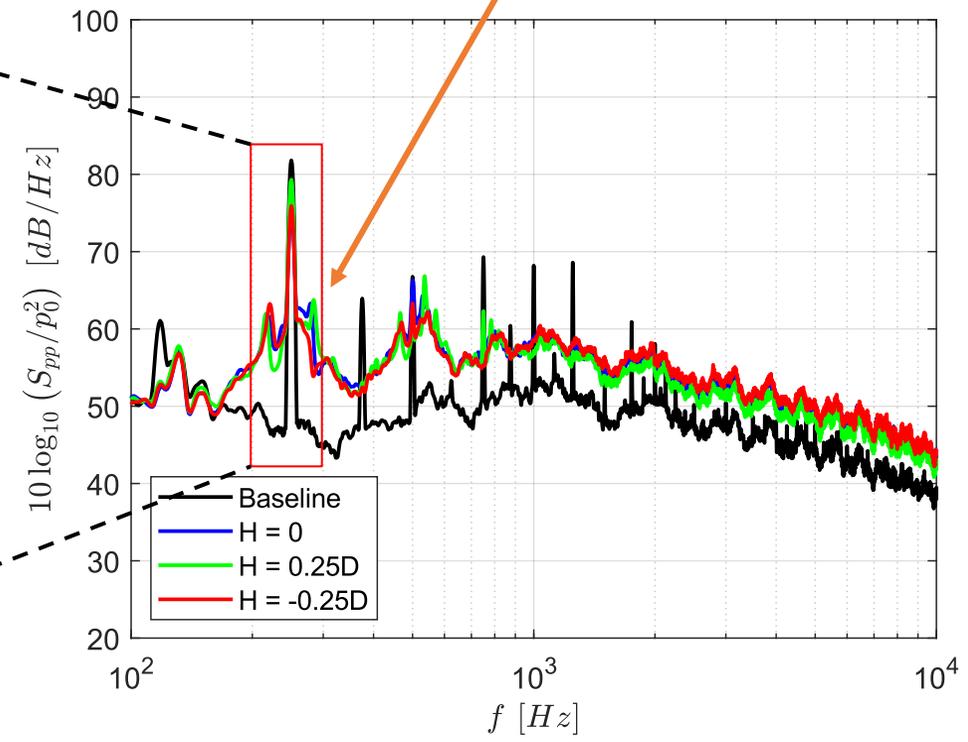
Results and Discussion – Haystacking

7500 RPM and 20 m/s inflow ($\mu = 0.167$)

40 Hz



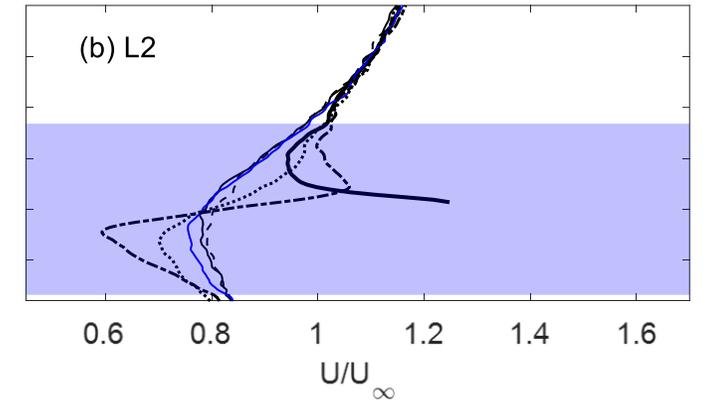
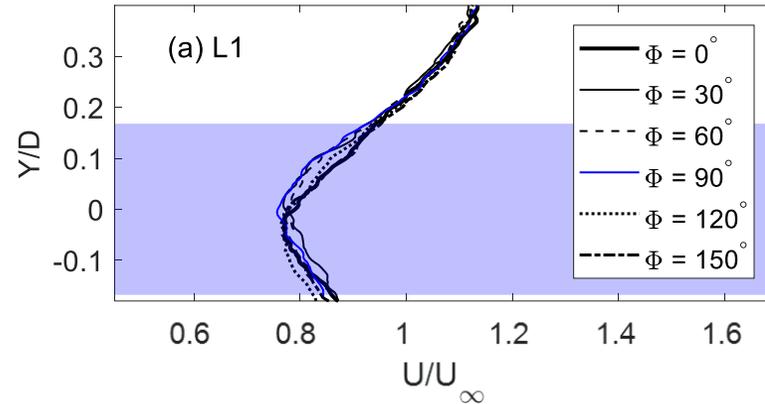
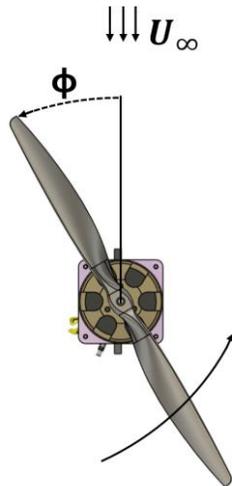
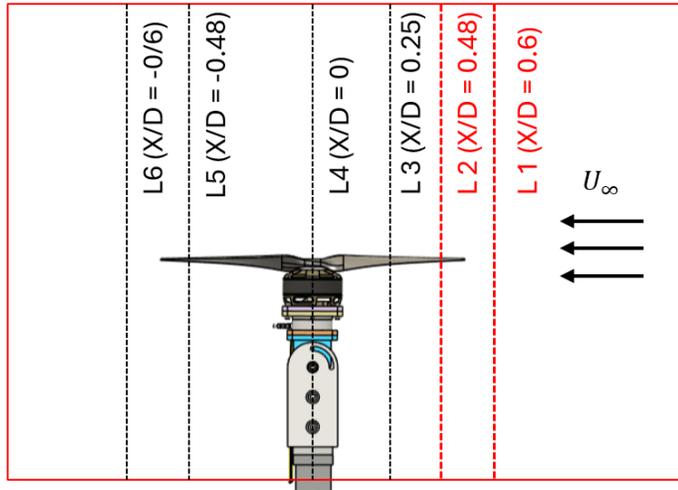
Evidence of Haystacking



- Overall SPL increase in all 3 cases
- Haystacking observed in the BPF

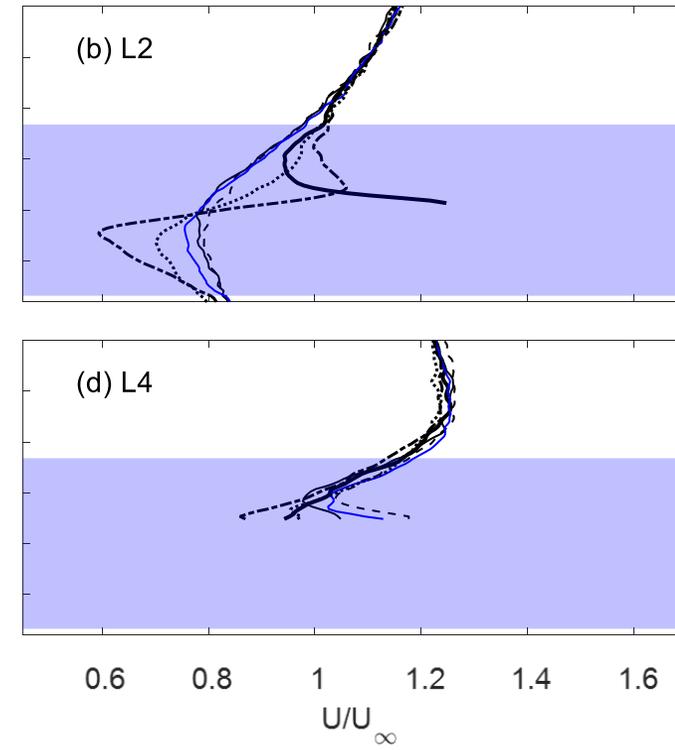
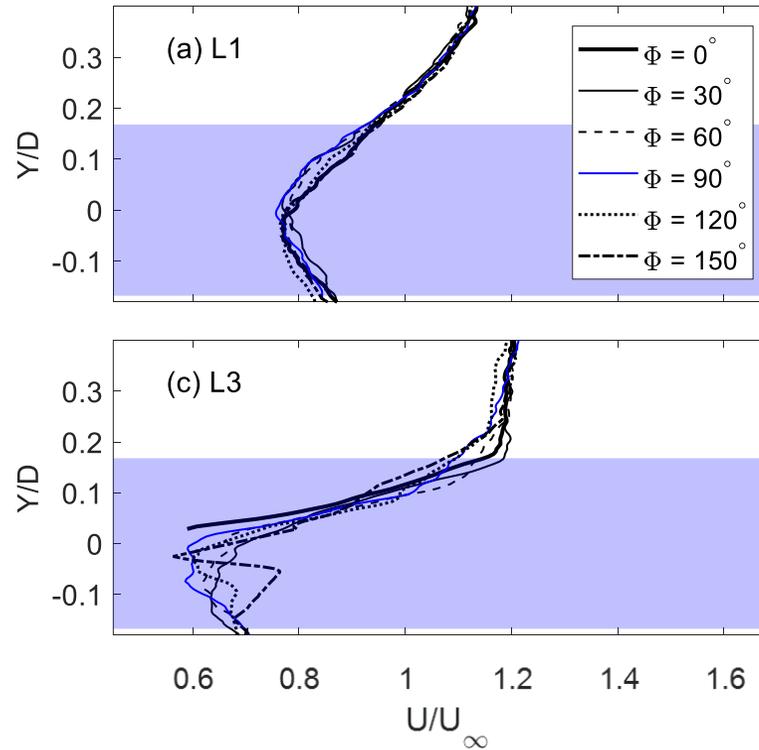
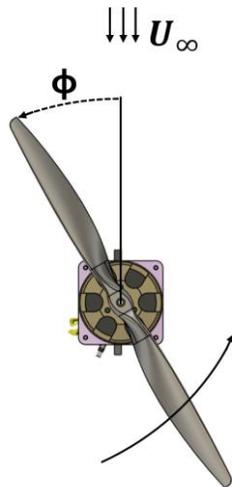
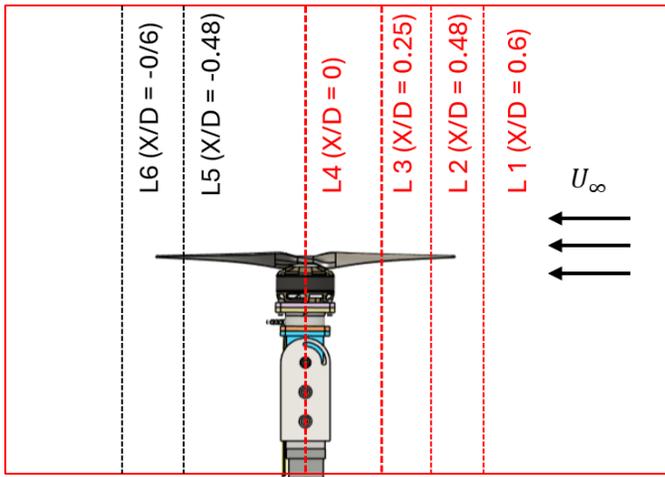
Results and Discussion – Far-field Noise Spectra

7500 RPM, 20 m/s inflow ($\mu = 0.167$) and $H=0$



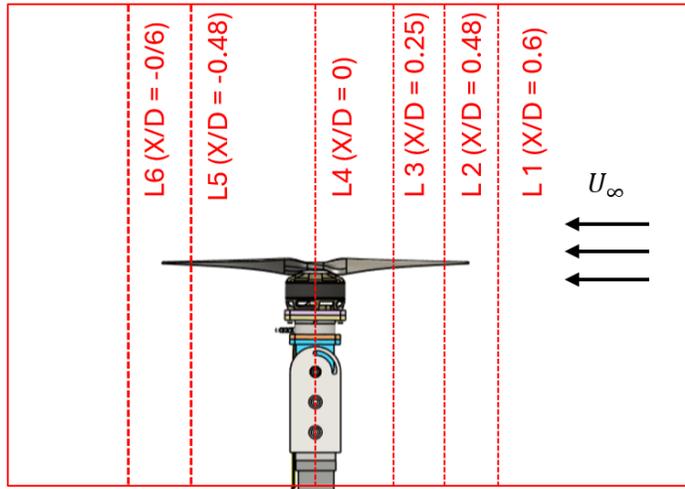
Results and Discussion – Far-field Noise Spectra

7500 RPM, 20 m/s inflow ($\mu = 0.167$) and $H=0$

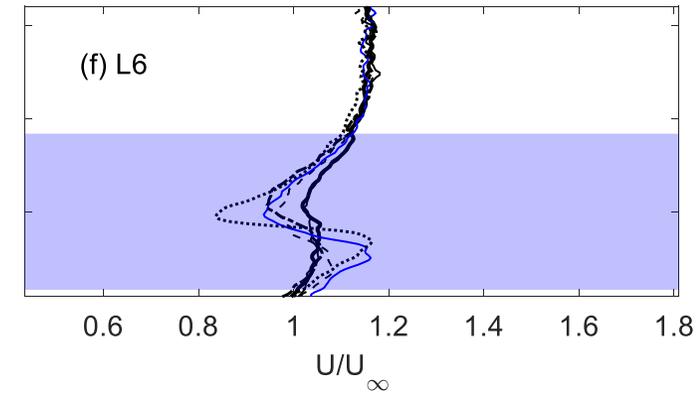
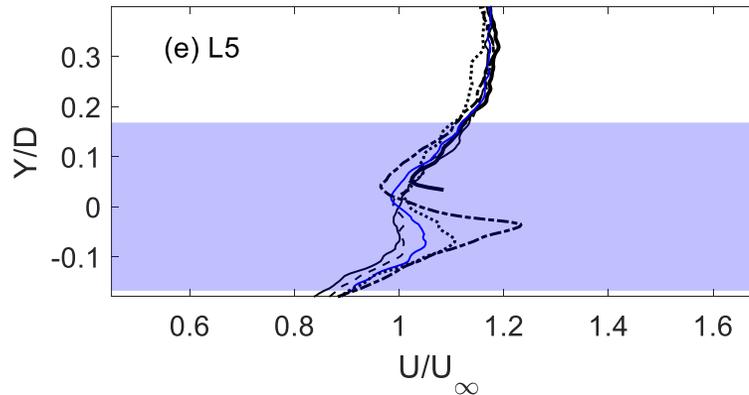
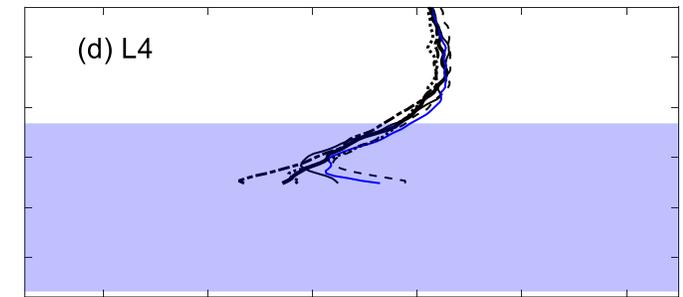
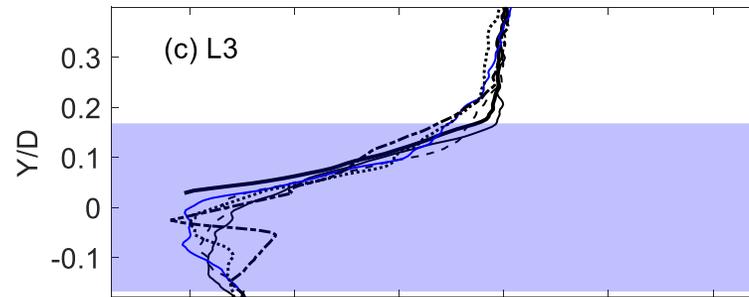
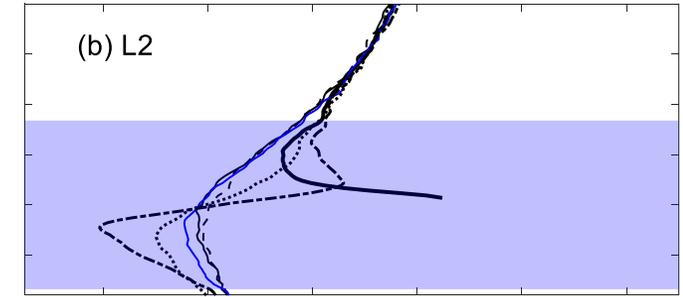
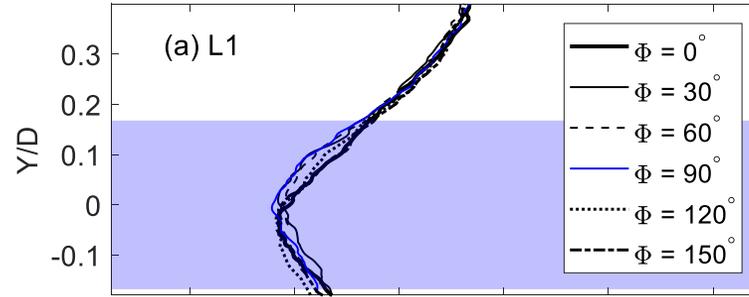
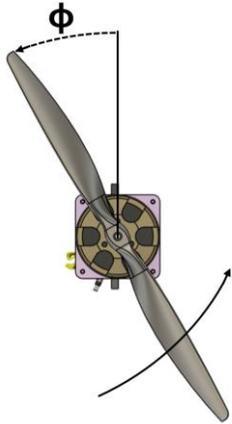


Results and Discussion – Far-field Noise Spectra

7500 RPM, 20 m/s inflow ($\mu = 0.167$) and $H=0$



U_∞



Overview

Background of tandem-rotor noise

Test overview and methodology

Results and discussion

Conclusions

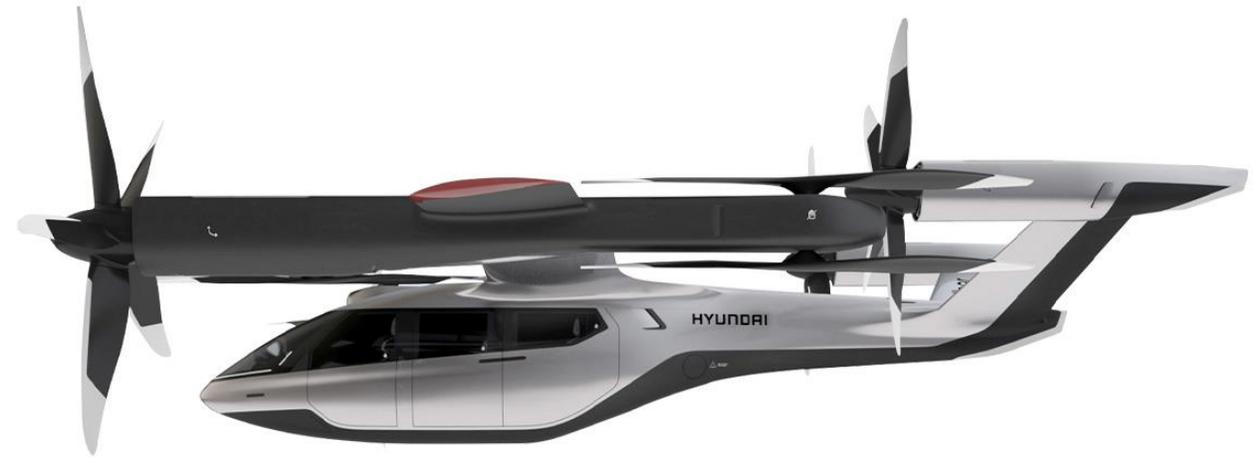
Future work



Conclusions

Successfully carried out acoustic and phase-locked PIV experiments investigating turbulence interactions on a UAM rotor in Edgewise flight

- Pinpoint the underlying drivers of haystacking
- Exceeded experimental capabilities
 - Successfully conducted phase locked PIV at 7,500 RPM
- Made available data for use in numerical models



Hyundai PAV

Future work

Extended test cases

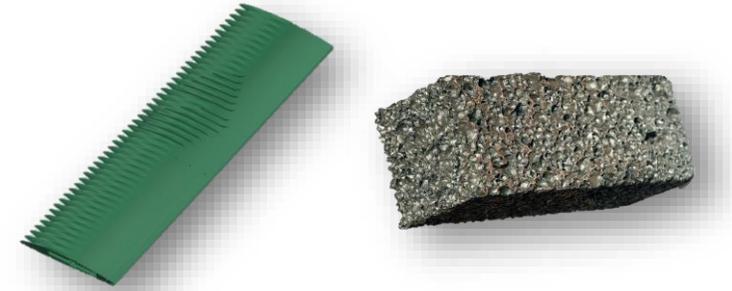
- Full PIV characterization of various cylinder configurations
- Phase-locked acoustic measurements

Numerical methods

- Creation of analytical models to predict changes in noise and performance of the propeller
- Validation of CFD methods

Noise mitigation methods

- Blade optimisation for noise mitigation (tip geometry, TE serration, etc.)



Examples of noise mitigation methods



© Glenn Bartholomew

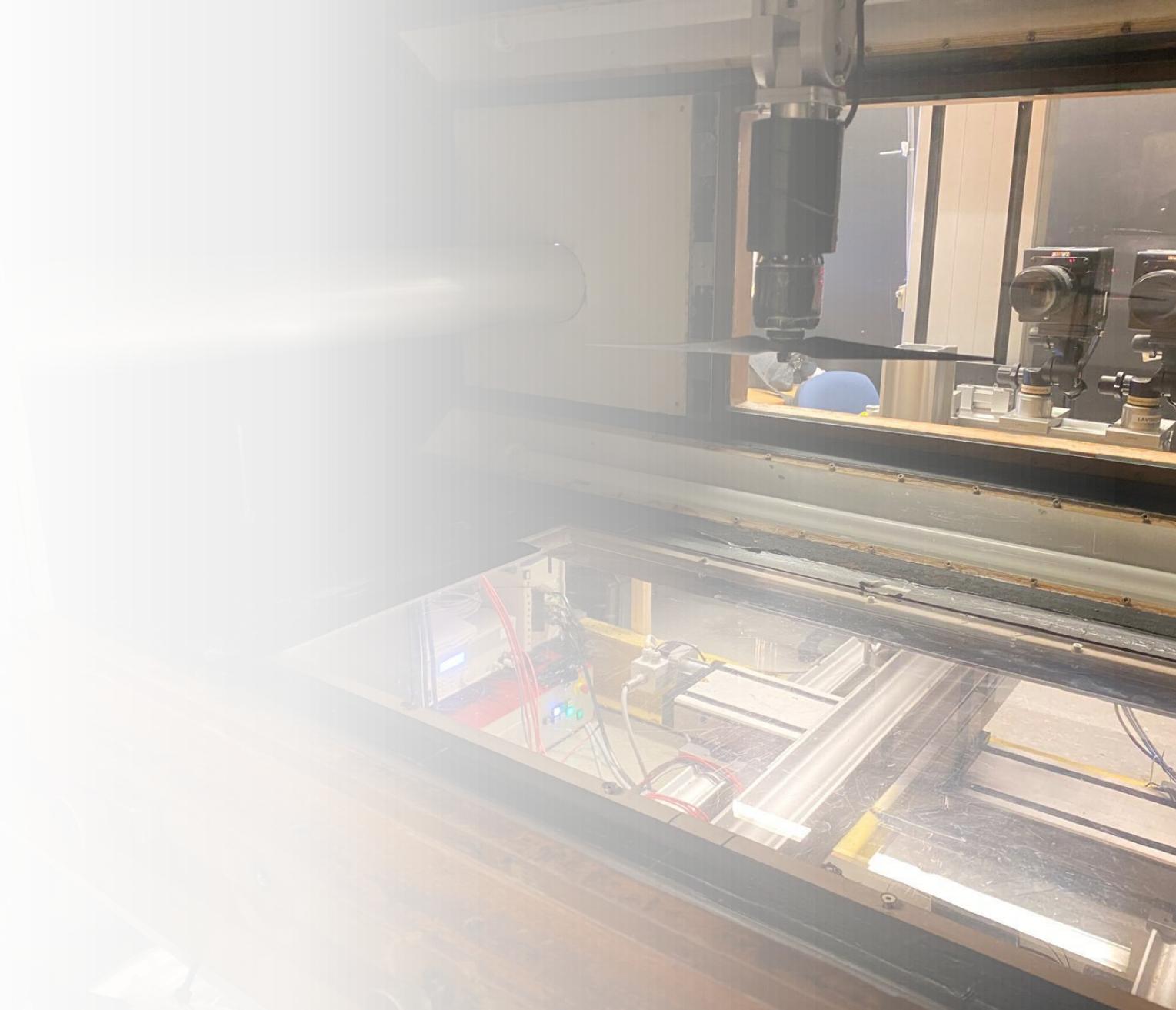
BERP, the most famous blade tip optimisation case

Thank you

Acknowledgements:

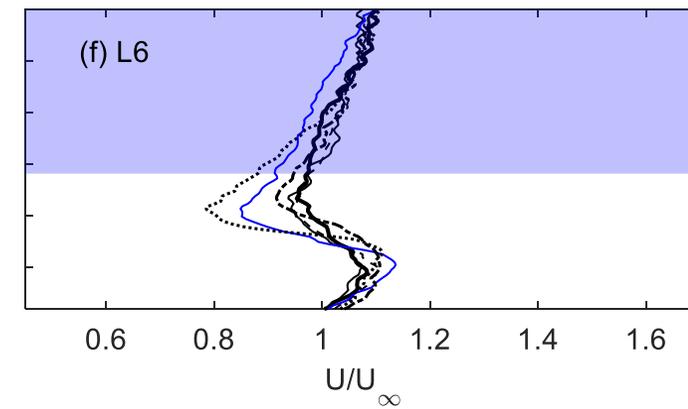
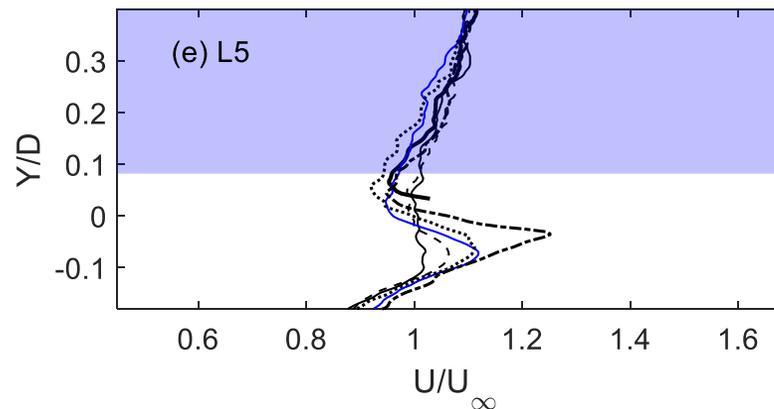
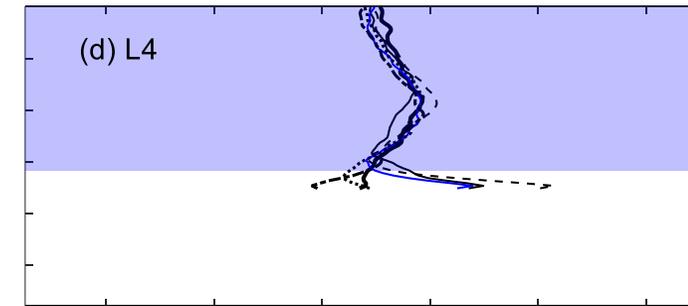
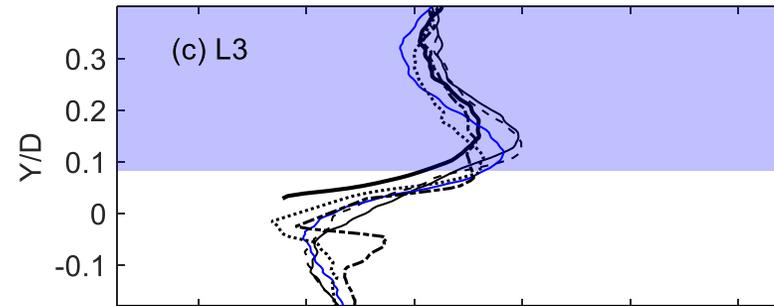
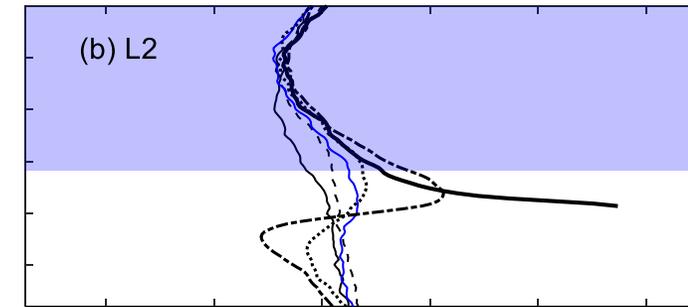
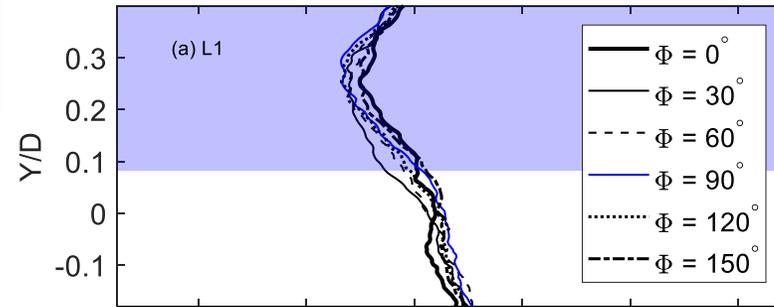
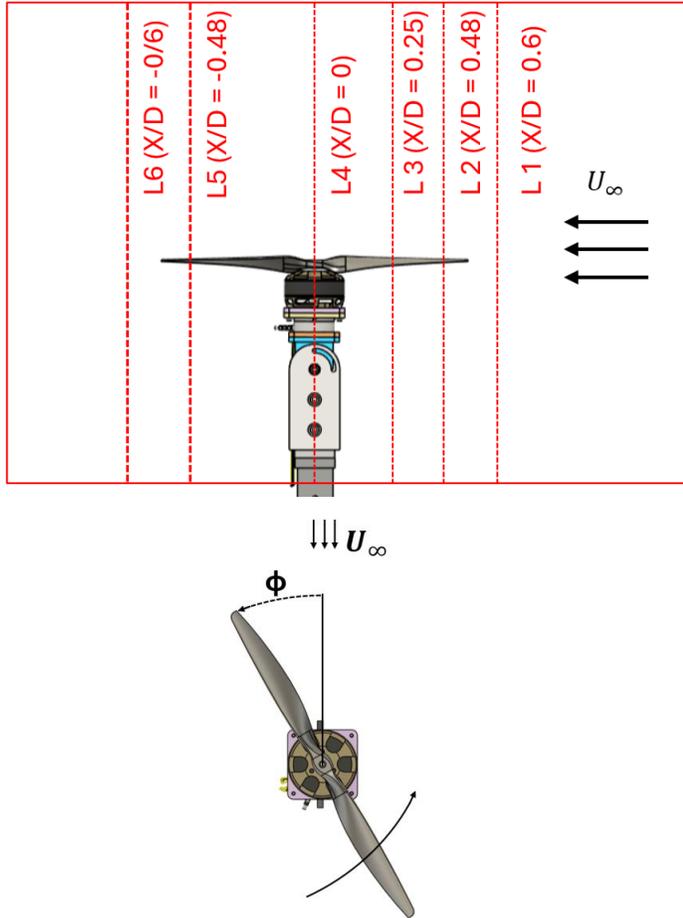
- RP4 Supervisor: Mahdi Azarpeyvand
- University of Bristol team: Xiao Liu, Lab technicians & Workshop team.

APPENDIX



Results and Discussion – Far-field Noise Spectra

7500 RPM, 20 m/s inflow ($\mu = 0.167$)
and $H=0.25D$



Results and Discussion – Far-field Noise Spectra

7500 RPM, 20 m/s inflow ($\mu = 0.167$)
and $H = -0.25D$

